



DATA SHEET

DFS60B-S4PK10000

DFS60
Incremental encoders

SICK Sensor Intelligence



Illustration may differ

INCREMENTAL ENCODERS

DFS60B-S4PK10000

ORDERING INFORMATION

Type	part no.
DFS60B-S4PK10000	1036722

Further device versions and accessories at www.sick.com/DFS60



DETAILED TECHNICAL DATA

SAFETY-RELATED PARAMETERS

MTTF _D (mean time to dangerous failure)	300 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

PERFORMANCE

Pulses per revolution	10,000 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

¹⁾ See maximum revolution range.

INTERFACES

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	32 ms, 30 ms ¹⁾
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

¹⁾ With mechanical zero pulse width.

ELECTRONICS

Connection type	Cable, 8-wire, universal, 1.5 m ¹⁾
Supply voltage	4.5 ... 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ^{2) 3)}

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

²⁾ Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

³⁾ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

MECHANICS

Mechanical design	Solid shaft, face mount flange
Shaft diameter	10 mm With flat
Shaft length	19 mm
Weight	+ 0.3 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.5 Ncm (+20 °C)
Operating torque	0.3 Ncm (+20 °C)
Permissible shaft loading	80 N (radial) 40 N (axial)
Operating speed	$\leq 9,000 \text{ min}^{-1}$ ¹⁾
Moment of inertia of the rotor	6.2 gcm ²
Bearing lifetime	3.6 x 10 ¹⁰ revolutions
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

AMBIENT DATA

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +100 °C ¹⁾ -30 °C ... +100 °C ²⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ Stationary position of the cable.

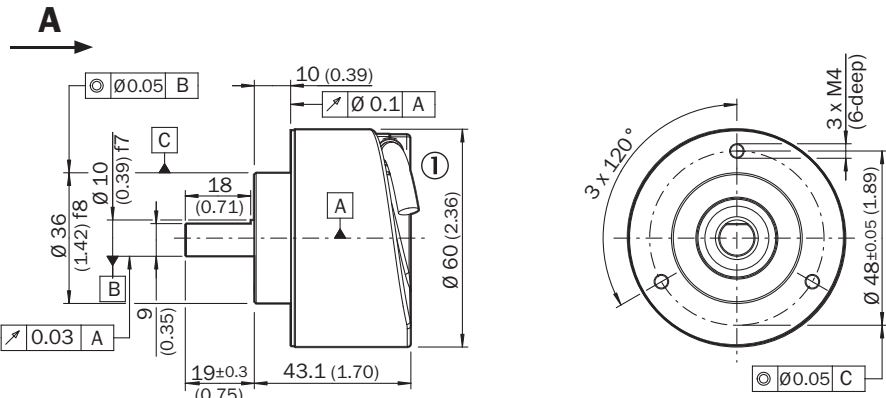
²⁾ Flexible position of the cable.

CERTIFICATES

UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓

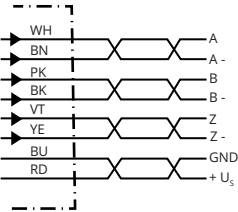
China RoHS	✓
cULus certificate	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

DIMENSIONAL DRAWING



Dimensions in mm (inch)
① cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

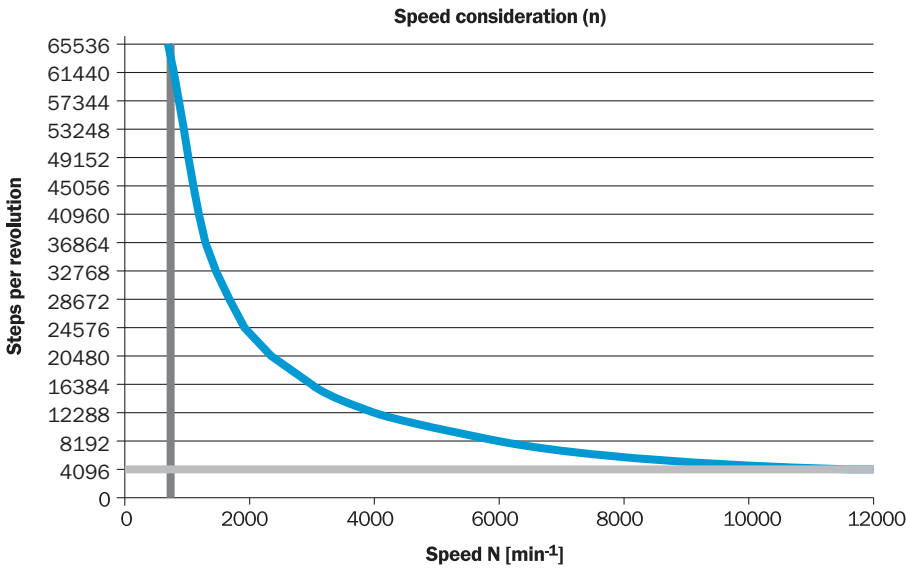
PIN ASSIGNMENT



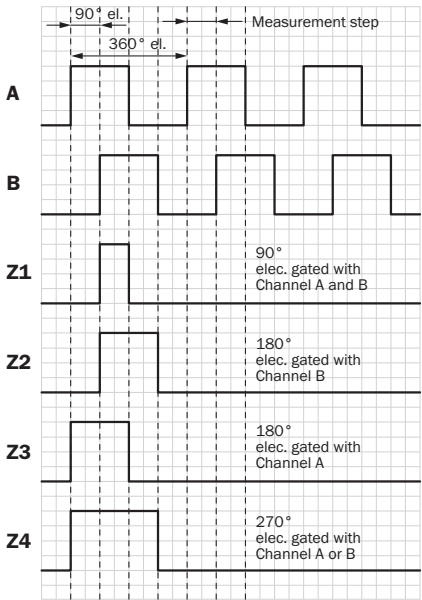
PINMale connec- tor M12, 8-pin	PINMale connec- tor M23, 12-pin	Wire colors (ca- ble connection)	TTL/HTL signal	Sin/Cos 1.0 V _{pp}	Explanation
1	6	Brown	A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	B	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	Z	Z	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U _s	+U _s	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 ¹⁾	Orange	0-SET ¹⁾	N.c.	Set zero pulse ¹⁾
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

¹⁾ For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

MAXIMUM REVOLUTION RANGE



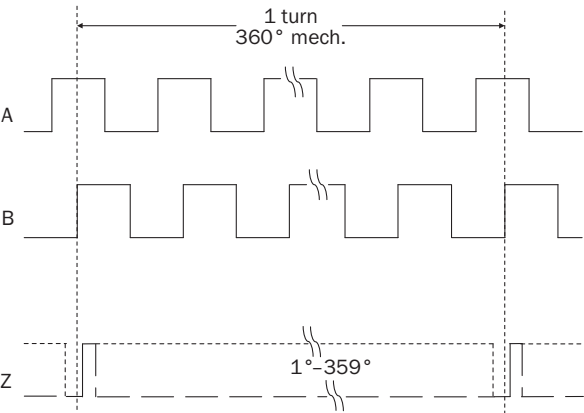
DIAGRAMS ELECTRICAL ZERO PULSE WIDTH CAN BE CONFIGURED TO 90°, 180°, OR 270°. WIDTH OF THE ZERO PULSE IN RELATION TO A PULSE PERIOD.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V ... 32 V	TTL/HTL programmable

DIAGRAMS MECHANICAL ZERO PULSE WIDTH 1° TO 359° PROGRAMMABLE. WIDTH OF THE ZERO PULSE IN RELATION TO A MECHANICAL REVOLUTION OF THE SHAFT.



Supply voltage	Output
4,5 V ... 32 V	TTL/HTL programmable

Further information as well as suitable accessories, example applications and downloads such as CAD dimensional models, operating instructions and software can be found at www.sick.com/1036722



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SICK AT A GLANCE

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Since 1946, we have been developing innovative technologies with passion and a pioneering spirit. With a global network in around 40 countries, SICK has a global presence and is always close by. The company's headquarters are located in Waldkirch near Freiburg, Germany. Our customers benefit from our understanding of both local and global requirements, which enables us to deliver tailor-made solutions

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